

LF-B10R series

Zoom Cabin User Manual V1.1



catalogue

Revise Resume 3 3

1. Product Overview 4 4

 1.1. Product Introduction 4 4

 1.2. Packing List 4 4

2. Technical Parameters 5 5

 2.1. Overall Parameters 5 5

 2.2. Zoom Camera 5 5

 2.3. Cloud Platform 5 5

3. Function Introduction 6 6

 3.1. Photo and Video Recording Function 6 7

 3.2. Camera Functions 6 7

 3.3. Other Functions 7 7

4. Notes 7 7

 4.1. Daily Maintenance 7 8

 4.2. Usage Instructions 8 9

Revise resume

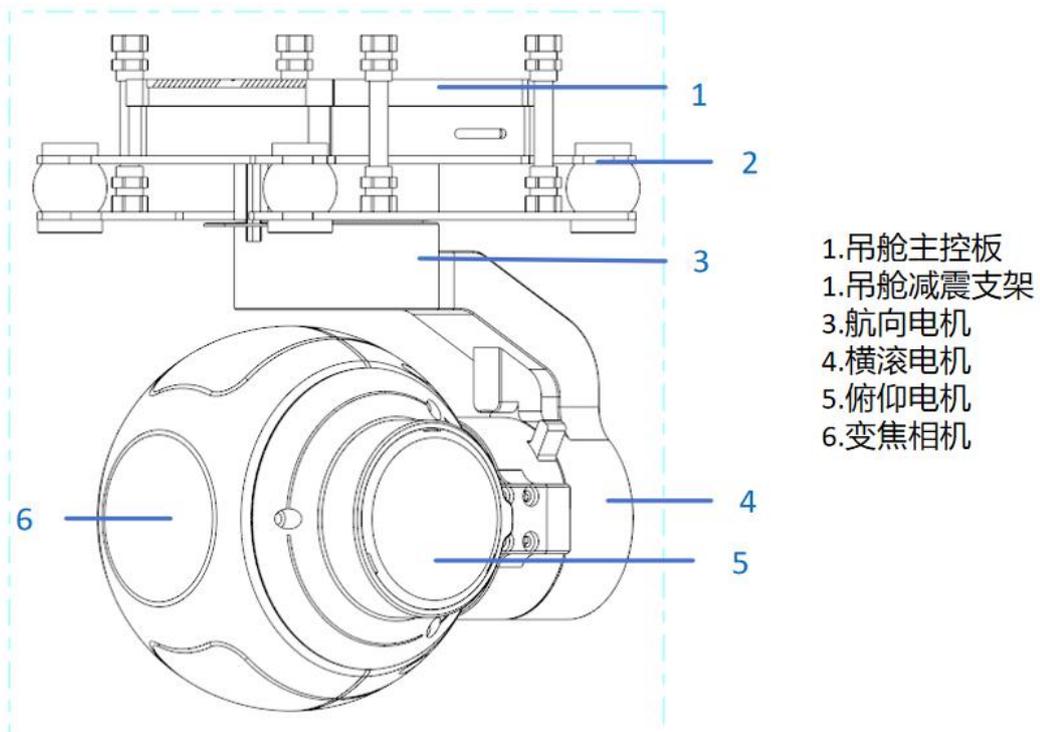
version number	Revision date	Revision
V1.0	2025/9/10	-First release
V1.1	2025/2/6	-Add 1.2 component description -Add 2.4 structural shape diagram -Add 3 features -Add 4 pod usage instructions

1. Product Overview

1.1. Product Introduction

The LF-B10R series is a zoom gimbal featuring 10x ultra-HD optical zoom. Powered by an SOC processor with a neural network engine and built-in AI algorithms, it excels in target detection and tracking. Equipped with a lightweight three-axis gimbal and adaptive damping module, along with autofocus and gimbal stabilization algorithms, it ensures stable and clear footage during aerial operations.

1.2. Component Description



1.3. container loading list

order number	name	model	unit	quantity	remarks
1	zoom pod	LF-B10R	tower	1	
2	packing chest	packing chest	cover	1	

2. technical parameter

2.1. Overall parameters

video output interface	Ethernet port
control signal interface	1 S.BUS, 1 serial port, and 1 Ethernet port
Power supply area	10V ~ 28V
System power consumption	Average power consumption: ≤15W
levels of protection	IP4X
working temperature	-20°C~55°C
Size (excluding shock absorbers)	79x100x118mm
mechanical interface type	lashing eye

2.2. Zoom camera

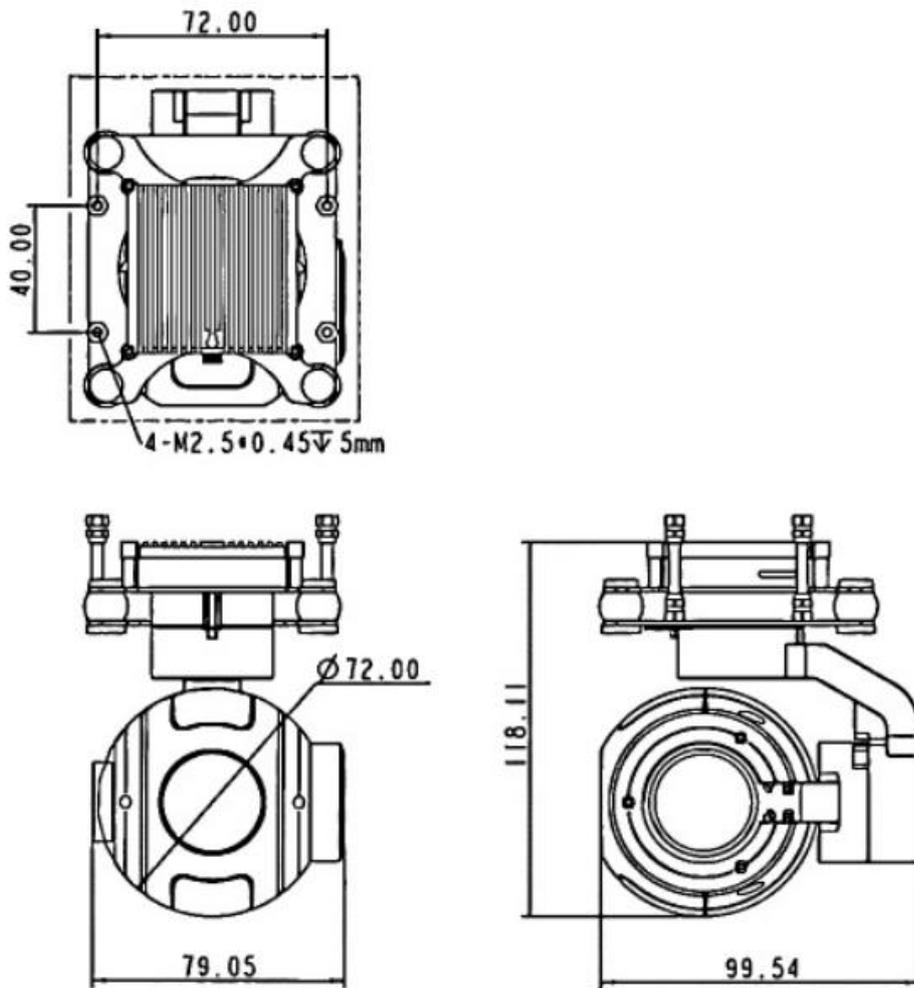
imaging sensor	8 million pixels			
Maximum photo size	3840*2160 (4:3)			
Video resolution	3840×2160@30fps、1920×1080@30fps			
coded format	H.264、H.265			
Focus mode	MF、AFS			
effective focal length	5.0mm-47.8mm			
equivalent focal length	33.87mm-323.76mm			
iris diaphragm	F2.1-F3.2			
optical zoom	10 times			
angle of field	focal distance	DFOV	HFOV	VFOV
	Wide	65.1°	58.2°	34.8°
	Tele	7.6°	6.7°	3.8°

2.3. Cloud Terrace

stabilization system	3 axes (pitch, roll, heading)
----------------------	-------------------------------

range of rotation	cabrage	roll	azimuth
	-90° ~ +30	±30°	±160°
stability accuracy	≤0.01°		
work pattern	Follow and Lock		

2.4. Structural shape diagram



3. function Introduction

3.1. Photo and video recording

- Single shot: Take one photo after clicking the take button.
- Continuous shooting: Take photos at fixed intervals after clicking.

- Photo resolution: Supports 3840*2160 and 1920*1080 resolutions.
- Video recording resolution: Supports 3840*2160@30fps and 1920*1080@30fps.

3.2. Camera features

3.2.1. Zoom control

- Zoom: Supports up to 10x optical zoom.
- Focus modes: supports MF and AFS.

3.2.2. Dehaze Mode

- Electronic defogging: The mode supports three customizable levels—low, medium, and high.

3.3. Other features

3.3.1. memory card

- Supports microSD cards up to 128GB, compatible with FAT32 and ExFAT file systems.

4. Signal line description

4.1.8-pin external ports: motherboard serial and USB

order number	definition	explain	Wiring harness color	remarks
1	FLY-RXD	flight control communication serial port receiving	hispid arthraxon	
2	FLY-TXD	flight control communication serial port transmission	Huang	
3	GND	earth wire	black	
4	URT0-RX	debugging serial port receiving	Lan	
5	URT0-TX	debug serial transmission	Huang	
6	GND	earth wire	black	
7	USB-DP	USB 2.0 signal positive	palm	
8	USB-DN	USB 2.0 signal negative	Huang	

4.2. Mainboard power supply, 9-pin external network port

order number	definition	explain	Wiring harness color	remarks
1	LAN-TX-P	100 megabit network port signal	Huang	

2	LAN-TX-N	100 megabit network port signal	hispid arthraxon	
3	LAN-RX-P	100 megabit network port signal	Lan	
4	LAN-RX-N	100 megabit network port signal	hispid arthraxon	
5	NC	hang in the air		
6	GND	earth wire	black	
7	GND	earth wire	black	
8	VBAT	power input	red	
9	VBAT	power input	red	

5. matters need attention

5.1. maintenance overhaul

5.1.1. Daily Use and Cleaning

- Dust and dirt protection

Avoid contaminating the lens with chemicals or oil during use. Clean the lens surface immediately after use with a lens cloth.

Direct wiping of optical lenses with hands or rough fabrics is prohibited. It is recommended to use professional lens cleaning kits, dust-free cloths, or alcohol for cleaning.

- Moisture-proof and waterproof

Avoid prolonged use in rainy, snowy, or high-humidity environments. If exposed to damp conditions, wipe the surface with a dry soft cloth after operation and store in a dry environment.

Do not soak or rinse the device directly.

- collision and vibration protection

During transportation or storage, place the pod in the factory-provided explosion-proof box to keep it securely fixed and protect it from violent shaking or dropping.

Do not impact the lens with sharp or hard objects, as this may cause damage and affect its performance.

5.1.2. matters need attention

- Do not disassemble by yourself

Non-professionals must not disassemble the pod's core components (e.g., optical modules or circuit boards), as doing so may cause damage or void the warranty.

- exception handling

If the device exhibits abnormal overheating, unusual noises, or image distortion, stop using it immediately and contact after-sales technical support.

Do not force the device to start in a faulty state.

5.2. Usage Notes

5.2.1. Preparation before use

- Environmental inspection

Maintain the operating environment temperature within -20°C to 55°C, and avoid areas with strong electromagnetic interference.

The use is prohibited during severe weather conditions such as rain, snow, and sandstorms.

- equipment inspection

Check the pod for damage, the lens for stains, and the gimbal for smooth rotation without noise.

Inspect the mechanical structure of the flywheel gimbal for looseness. If any abnormal response is detected, immediately deactivate and perform maintenance.

Check the electrical connections of the system.

Check the normality of the gimbal imaging and function.

5.2.2. Usage Notes

If there are any abnormal situations such as abnormal picture or abnormal control of the pan-tilt unit during the operation, the operation task should be stopped and returned to the ground for inspection.

5.2.3. Post-processing

After use, the system must be powered down before the pod can be removed from the aircraft.

After cleaning the lens, it was put back into the packaging box.